

Announcements

- 1) Can turn in HW 1 until 8 today
- 2) HW 2 up on canvas,
due next Thursday

Generating Sets

Let \mathcal{V} be a vector space over \mathbb{F} . A subset S of \mathcal{V} is called **generating** (or **spanning**) for \mathcal{V} if $\text{span}(S) = \mathcal{V}$ (span is over \mathbb{F}).

Example 1 :

(homogeneous systems
of linear equations)

Consider a system of
homogeneous linear equations

$$a_{1,1}x_1 + a_{1,2}x_2 + \cdots + a_{1,n}x_n = 0$$

$$a_{2,1}x_1 + a_{2,2}x_2 + \cdots + a_{2,n}x_n = 0$$

⋮

$$a_{m,1}x_1 + a_{m,2}x_2 + \cdots + a_{m,n}x_n = 0$$

where $a_{i,j}$ is either real or complex for all $1 \leq i \leq m$ and $1 \leq j \leq n$.

The Solution Space

to the system is all vectors (y_1, y_2, \dots, y_n) in either \mathbb{R}^n or \mathbb{C}^n such that

$$\sum_{j=1}^n a_{i,j} y_j = 0 \quad \text{for all } 1 \leq i \leq m$$

The solution set
is a subspace
of \mathbb{R}^n or \mathbb{C}^n
(use subspace test).

A generating set can
be obtained for the
solution set - but I
need words I
haven't defined yet!

Example 2: (frames in \mathbb{R}^n)

A finite subset

$$S = \{w_1, w_2, \dots, w_k\}$$

of \mathbb{R}^n that is spanning

and satisfies the

frame condition.

$\exists A, B \in \mathbb{R}^+$ such that

$$\forall v \in \mathbb{R}^n,$$

$$A \|v\| \leq \sum_{i=1}^k |N \cdot w_i|^2 \leq B \|v\|$$

Here " $v \cdot v$ " is

the usual dot

product on \mathbb{R}^n .

If $v = (v_1, \dots, v_n)$

$v = (v_1, \dots, v_n)$,

$$v \cdot v = \sum_{i=1}^n (v_i v_i) .$$

BMW frame

$$S \subseteq \mathbb{R}^2$$

$$S = (\omega_1, \omega_2, \omega_3)$$

where

$$\omega_1 = (\cos(60^\circ), \sin(60^\circ))$$

$$\omega_2 = (\cos(180^\circ), \sin(180^\circ))$$

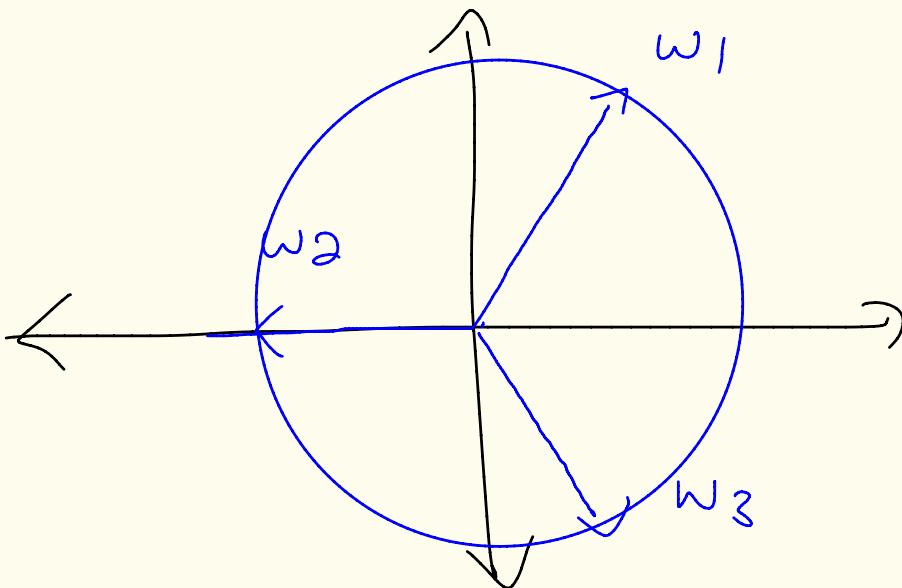
$$\omega_3 = (\cos(300^\circ), \sin(300^\circ))$$

$$\omega_1 = \left(\frac{1}{2}, \frac{\sqrt{3}}{2} \right)$$

$$\omega_2 = (-1, 0)$$

$$\omega_3 = \left(\frac{1}{2}, -\frac{\sqrt{3}}{2} \right)$$

Picture



$$\omega_1 - \omega_3 = (0, \sqrt{3})$$

$$\omega_2 = (-1, 0)$$

so if $(\alpha, \beta) \in \mathbb{R}^2$,

$$(\alpha, \beta) = -2\omega_2$$

$$+ \frac{\beta}{\sqrt{3}} (\omega_1 - \omega_3).$$

This shows S is
spanning for \mathbb{R}^2 .

Frame Condition

$$\mathbf{v} = (v_1, v_2, v_3)$$

$$|\mathbf{v} \cdot \omega_1| = \left| \frac{v_1 + \sqrt{3}v_2}{2} \right|$$

$$|\mathbf{v} \cdot \omega_3| = \left| \frac{v_1 - \sqrt{3}v_2}{2} \right|$$

$$|\mathbf{v} \cdot \omega_2| = |v_1|$$

Squaring each term and adding yields

$$\frac{3v_1^2}{2} + \frac{3v_2^2}{2}, \text{ so}$$

we could choose A=B=3/2.

Example 3: (non-spanning set)

$$S = \{(1, 2, 4), (-1, 0, 1)\}$$

is **not** a spanning
set for \mathbb{R}^3 .

Matrix techniques

Show this.

Linear Independence

(Section 1.5)

Notation: $(\hat{e}_i)_{i=1}^n$

\hat{e}_i is the vector in \mathbb{R}^n is the vector in \mathbb{R}^n

with a one in the i^{th} position and zeros in all other positions.

If we fix any i ,
 $1 \leq i \leq n$, then \hat{e}_i is
not in the Span of

$\{\hat{e}_j\}_{1 \leq j \leq n}$ because
 $i \neq j$

all of these vectors
have zero in the i^{th}
position

Definition: (linear independence)

Let \mathcal{V} be a vector space over \mathbb{F} . A nonempty subset S of \mathcal{V} is called linearly independent (over \mathbb{F}) if

$\forall x_1, x_2, \dots, x_n \in S,$

$x_i \neq 0_{\mathbb{F}} \wedge \underbrace{\sum_{i=1}^n \alpha_i x_i = 0_{\mathbb{F}}}_{\text{then if}}$

for some scalars $\alpha_1, \dots, \alpha_n$ then

$$\alpha_1 = \alpha_2 = \cdots = \alpha_n = 0_{\mathbb{F}}$$

Note: this is equivalent
to saying that whenever
you take $x \in S$, $x \neq 0_V$,
then $x \notin \text{Span}(S \setminus \{x\})$.

We have already shown
that $(e_i^{\wedge})_{i=1}^n$ is
linearly independent over
 \mathbb{R} . When no confusion
arises, we'll drop the
superscript " \wedge " and just
write $(e_i)_{i=1}^n$.

Example 4: (matrix units)

In $M_n(\mathbb{R})$ or $M_n(\mathbb{C})$, if

we let $e_{i,j}$ be

the matrix with a
one in the (i,j) position
and zeros elsewhere,

then $\{e_{i,j}\}_{i,j=1}^n$ is

linearly independent over

\mathbb{R} or \mathbb{C} .

Example 5 : (monomials)

Let V be the vector space of polynomials with real coefficients (over \mathbb{R}). The set $S = \{x^n \mid n \geq 0\}$ ($n \in \mathbb{N}$)

is linearly independent over \mathbb{R} .

If $\alpha_0, \alpha_1, \dots, \alpha_n \in \mathbb{R}$

and $\sum_{i=0}^n \alpha_i x^i = 0$,

then as a function on \mathbb{R} ,

$f(x) = \sum_{i=0}^n \alpha_i x^i$ is the zero

function. This

implies $\alpha_0 = \alpha_1 = \dots = \alpha_n = 0$

since x can be any real number.

By the fundamental

theorem of algebra,

f has at most n

zeros, contradiction.

Therefore the monomials

$\{x^n\}_{n=0}^{\infty}$ are

linearly independent

over \mathbb{R} .

Example 6 (linearly dependent set)

Let x be any vector
in a vector space \checkmark
over a field \mathbb{F} .

Then if x is any scalar, $x \neq 0_{\mathbb{F}}$,
 $\alpha \neq 1_{\mathbb{F}}, 0_{\mathbb{F}}$

then $\{x, \alpha x\}$ is linearly dependent.

Bases and Dimension

(section 1.6)

A basis for a vector

Space V over a field F

is a maximal linearly

independent subset of

V .

Maximal = not contained in
any larger linearly
independent set.

Consequence: any basis
for V over \mathbb{F} must
be spanning for V .